



-L- PI Sta 878+23.42 Δ = 11° 59' 57" D = 24000' L = 16000' T = 8000' SE = 04' DS = 70 MPH	-L- PI Sta 881+92.35 Δ = 5° 46' 23.6" (RT) D = 0 59' 35.9" L = 571.3' T = 288.5' SE = 04' DS = 70 MPH	-L- PI Sta 885+60.79 Δ = 11° 59' 57" D = 24000' L = 16000' T = 8000' SE = 04' DS = 70 MPH	-L- PI Sta 15+00.00 Δ = 11° 59' 57" D = 24000' L = 16000' T = 8000' SE = 04' DS = 70 MPH	-L- PI Sta 15+00.00 Δ = 11° 59' 57" D = 24000' L = 16000' T = 8000' SE = 04' DS = 70 MPH	-L- PI Sta 15+00.00 Δ = 11° 59' 57" D = 24000' L = 16000' T = 8000' SE = 04' DS = 70 MPH
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-Y42RPA- PI Sta 15+00.00 Δ = 11° 59' 57" D = 24000' L = 16000' T = 8000' SE = 04' DS = 70 MPH	-Y42RPA- PI Sta 15+00.00 Δ = 11° 59' 57" D = 24000' L = 16000' T = 8000' SE = 04' DS = 70 MPH	-Y42RPA- PI Sta 15+00.00 Δ = 11° 59' 57" D = 24000' L = 16000' T = 8000' SE = 04' DS = 70 MPH	-Y42RPA- PI Sta 15+00.00 Δ = 11° 59' 57" D = 24000' L = 16000' T = 8000' SE = 04' DS = 70 MPH	-Y42RPA- PI Sta 15+00.00 Δ = 11° 59' 57" D = 24000' L = 16000' T = 8000' SE = 04' DS = 70 MPH	-Y42RPA- PI Sta 15+00.00 Δ = 11° 59' 57" D = 24000' L = 16000' T = 8000' SE = 04' DS = 70 MPH
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-Y4- PI Sta 12+47.58 Δ = 3° 23' 10.7" (LT) D = 0 27' 36.7" L = 755.0' T = 381.0' R = 12,450.0' SE = NC
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-SRT- PI Sta 11+17.71 Δ = 54° 38' 43.3" (RT) D = 38' 11" 49.9" L = 143.0' T = 77.50' SE = 02' DS = 15 MPH	-SRT- PI Sta 12+29.39 Δ = 107° 32' 21.7" (LT) D = 11' 27' 33.0" L = 51.97' T = 46.0' SE = 02' DS = 15 MPH	-SRT- PI Sta 13+45.23 Δ = 3° 49' 11.0" (RT) D = 20000' L = 13336' T = 6668' SE = 02' DS = 50 MPH	-SRT- PI Sta 12+39.28 Δ = 3° 49' 11.0" (RT) D = 20000' L = 13336' T = 6668' SE = 02' DS = 50 MPH	-SRT- PI Sta 11+33.36 Δ = 3° 49' 11.0" (RT) D = 20000' L = 13336' T = 6668' SE = 02' DS = 50 MPH
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-RABT1- PI Sta 10+00.00 Δ = 359° 59' 42.1" (LT) D = 124' 33" 21.8" L = 285.02' T = 0.00' R = 46.00' SE = 02' DS = 20 MPH	-RABT2- PI Sta 10+00.00 Δ = 359° 59' 42.1" (LT) D = 124' 33" 21.8" L = 285.02' T = 0.00' R = 46.00' SE = 02' DS = 20 MPH
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-PVTENT1- PI Sta 10+10.13 Δ = 11° 59' 57" (LT) D = 11' 35' 29.6" L = 45.3' T = 24.3' R = 5000'

-SR9- PI Sta 14+00.00 Δ = 35° 43' 23.2" (RT) D = 6° 52' 41.7" L = 533.9' T = 833.00' SE = 02' DS = 50 MPH	-SR9- PI Sta 20+59.81 Δ = 40° 52' 30.2" (LT) D = 3° 49' 49.9" L = 107.0' T = 55.90' SE = 02' DS = 15 MPH	-SR9- PI Sta 11+33.36 Δ = 3° 49' 11.0" (RT) D = 20000' L = 13336' T = 6668' SE = 02' DS = 50 MPH	-SR9- PI Sta 13+45.23 Δ = 3° 49' 11.0" (RT) D = 20000' L = 13336' T = 6668' SE = 02' DS = 50 MPH	-SR9- PI Sta 15+26.51 Δ = 3° 49' 11.0" (RT) D = 20000' L = 13336' T = 6668' SE = 02' DS = 50 MPH
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L. Rex Cooper, a Professional Land Surveyor in the state of North Carolina hereby certify to the best of my knowledge and belief that the following work items (RT/W Staking) performed under my responsible charge meet NCOSI Survey Standards as directed in the NCOSI Location & Surveys guidelines and procedures.

Further, I certify that the right of way and permanent easement points shown herein and outlined in the tapes shown herein, located coordinates, stationing or feet have been checked and are accurate representations of the right of way and permanent easement points depicted on the corresponding right-of-way plans. I also certify that the right of way and permanent easement points shown herein have been field monumented under my supervision from existing survey control provided by others that the depicted property data shown herein were surveyed by others and these monuments denote the right of way and easement boundaries at the time of staking which may be subject to change due to right of way revisions (see deeds for final determination).

Witness my original signature, registration number and seal this 4th day of April, 2022.

Digitally signed by: *L. Rex Cooper*
 DN: cn=L. Rex Cooper, o=L. Rex Cooper, ou=L. Rex Cooper, email=L. Rex Cooper@lrcs.com, c=US
 Digitally signed by: *L. Rex Cooper*
 DN: cn=L. Rex Cooper, o=L. Rex Cooper, ou=L. Rex Cooper, email=L. Rex Cooper@lrcs.com, c=US

- NOTES:**
- IF FURTHER INFORMATION REGARDING PROJECT CONTROL IS NEEDED PLEASE CONTACT THE LOCATION AND SURVEYS UNIT.
 - PROJECT CONTROL WAS ESTABLISHED USING GNSS, THE GLOBAL NAVIGATION SATELLITE SYSTEM.